

HP-29C Quick Reference

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Memory

Permanent memory	<ul style="list-style-type: none"> • 16 storage registers • X register • 98 program steps • Display format
Volatile memory	<ul style="list-style-type: none"> • 14 storage registers • Y, Z, T and Last-X registers • Trigonometric mode • Program counter

Storage

STO 0-9, .0-.5, i	Save data in one of the 16 permanent storage registers
STO +-x÷ 0-9, .0-.5, i	Register storage arithmetic: Register OP X → Register Register revall arithmetic is not supported
RCL 0-9, .0-.5, i	Retrieve data from one of the 15 permanent storage registers
Indirect addressing	<ul style="list-style-type: none"> • Volatile registers 16-29 can only be accessed via indirect addressing • R0 contains the index. Only the integer part of the absolute value of R0 will be used • Note that registers .0-.9 correspond to R0=10-15 • Press "STO i" or "RCL i" for indirect operations. i is located on the R↓ key and need not be prefixed
CLEAR REG	Clears all registers 0-29

Miscellaneous

FIX n	Select fixed point format with n digits after the decimal point
SCI n	Select exponential format with n valid digits
ENG n	Select exponential format where the exponent is always a multiple of 3. Note that with n=0 & 1 routing can occur <i>in front of</i> the decimal point!
DEG	Trigonometric mode degrees (360, default)
RAD	Trigonometric mode radians (2π)
GRD	Trigonometric mode grad (400)
y^x	Y to the power of X. Y may be negative if X is integer
→ H	Convert h.mms to fractional hours
→ H.MS	Convert fractional hours to h.mms format
→ R	Convert polar coordinates ($X=r, Y=\theta$) to orthogonal coordinates
→ P	Convert orthogonal coordinates to polar coordinates ($X=r, Y=\theta$)
%	Calculate X percent of Y. The stack doesn't drop!

Summation

Memory	6 summation registers mapped to the top non-volatile storage registers: n=R.0 $\Sigma x=R.1$ $\Sigma x^2=R.2$ $\Sigma y=R.3$ $\Sigma y^2=R.4$ $\Sigma xy=R.5$
CLEAR Σ	Clear summation registers
$\Sigma+$	Add X & Y to the sum registers and increment n
$\Sigma-$	Subtract X & Y from the sum registers and decrement n
\bar{x}	Calculate mean of X & Y values and put result in X & Y register
s	Calculate standard deviation of X & Y values and put result in X & Y register: $s_x = \text{SQRT} [\{ n \Sigma x^2 - (\Sigma x)^2 \} / \{ n(n-1) \}]$ and similar for sy

Programming

Memory	98 fully merged program steps Program does not halt when it encounters step 00!
PRGM/RUN	Use this switch to select programming or execution mode
CLEAR PRGM	RUN mode: Does nothing PRGM mode: Clear all program memory (fills with R/S instructions)
Program editing	<ul style="list-style-type: none"> • New instructions will be inserted after the currently displayed line • DEL deletes the currently displayed instruction and displays the previous line
SST & BST (RUN mode)	SST: Execute program step-by-step. While the key is held down the next instruction is displayed. When the key is released the instruction is executed BST: Same as SST except that no instructions are executed
SST & BST (PRGM mode)	Step forward/backward thru program instructions
LBL 0-9	Insert label. The same label can be used multiple times. Labels will be search from the current program counter towards the end of the program memory
GTO . nn	RUN or PRGM mode: Jump to line number nn
GTO 0-9	RUN mode: Set program counter to specified label 0-9 PRGM mode: Insert jump instruction to label 0-9
GTO i	RUN mode: Set program counter indirectly via R0 PRGM mode: Insert indirect jump instruction via R0 Only the integer part of R0 will be used: <ul style="list-style-type: none"> • R0=0..9: Jump to the specified label • R0<0: Jump back the given number of instructions in program memory
GSB 0-9, i	RUN mode: Execute program on specified label 0-9 or indirectly via R0 PRGM mode: Insert subroutine call to label 0-9 or indirect call via R0. At most 3 subroutine calls are possible
RTN	RUN mode: Set program counter to 00 PRGM mode: Insert return from subroutine instruction. At the top level this will halt the program and the program counter will point to the instruction after the RTN
PAUSE	Halt program for about 1 sec and display X register

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R/S	<p>RUN mode: Halt program. Note that in order to stop a program during a PAUSE you must hold the R/S key down until the pause is over!</p> <p>PRGM mode: Insert halt instruction</p>
DSZ	Decrement and skip if zero: Decrements R0 and if the integer part of the result is 0 skips the next program instruction
ISZ	Increment and skip if zero: Increments R0 and if the integer part of the result is 0 skips the next program instruction
Comparison	<p>These relational operators are available:</p> <p>$X < 0$ $X \geq 0$ $X \neq 0$ $X = 0$</p> <p>$X < Y$ $X \geq Y$ $X \neq Y$ $X = Y$</p> <p>If the relation is true the next program step is executed. If the relation is not true the next program step is skipped.</p>